

APPENDIX B

KEY'S TEN STEP ALGORITHM [92]

The Key's ten Step algorithm employed to compute the minimum reactive power required at receiving end is given as follows:

Step 1: Compute, $P_{r(crit)} = E_s^2 / X$

If $P_r^\circ > P_{r(crit)}$ no solution exists

If $P_r^\circ \leq P_{r(crit)}$ then go to **Step 2**

Step 2: Compute, $P_{r(max)} = P_r^\circ [100 / (100 - s.m_{des})]$

If $P_{r(max)} > P_{r(crit)}$ go to **Step 3**

If $P_{r(max)} \leq P_{r(crit)}$ go to **Step 4**

Step 3: Compute, $E_r^\circ = E_s$

$$\delta_r^\circ = -\sin^{-1} (P_r^\circ / P_{r(crit)}) \quad (B-1)$$

$$s.m.^\circ = (1 - P_{r(crit)}^\circ)100 \quad (B-2)$$

$$Q_m = P_{r(crit)} (1 - wxc)$$

(stop)

Step 4: Compute critical voltage ($E_{r(crit) s.m.}$) of the line limited by stability margin,

$$E_{r(crit)s.m.} = [P_{r(max)}^2 X^2 / E_s^2 + E_s^2 / 4 [1 - wxc]^2]^{1/2}$$

If $E_{r(crit)s.m.} \geq E_s$ the line is stability limited with

$$Q_m = [E_r^2 (1 - wxc) - F_s E_r \cos \delta_{r(max)}] / X$$

$E_{r(crit)} = E_s$ go to **Step 5**

If $\underline{E}_r < E_{r(crit)s.m.}$ the line is stability limited with

$$E_{r(\text{crit})} = E_{r(\text{crit})s.m.} \text{ Go to Step 6}$$

If $E_{r(\text{crit})s.m.} \leq \underline{E}_r$ the line is voltage limited with

$$E_{r(\text{max})} = \underline{E}_r \text{ go to Step 7}$$

Step 5: Computer $E_r^\circ = E_s$

$$\delta_r^\circ = \text{found from } (B - 1)$$

$$s.m.^\circ = s.m._{\text{des}}$$

$$\delta_{r(\text{crit})} = -\sin^{-1} (P_{r(\text{max})} / P_{r(\text{crit})})$$

$$\delta_m = P_{r(\text{crit})} (1 - wxc - \cos \delta_{r(\text{crit})})$$

(stop)

Step 6: Compute $E_{r(\text{max})} = E_{r(\text{crit})s.m.}$

$$\delta_{r(\text{max})} = -\sin^{-1} [P_{r(\text{max})} X / (E_{r(\text{max})} E_s)]$$

$$s.m.^\circ = s.m._{\text{des}}$$

$$Q_m = [E_{r(\text{max})} (1 - wxc) - E_s E_{r(\text{max})} \cos \delta_{r(\text{max})}] / X$$

go to **Step 8**

Step 7 : Compute,

$$\delta_{r(\text{max})} = -\sin^{-1} (X P_{r(\text{max})} / E_s \underline{E}_r)$$

$$\delta_{r(\text{crit})} = -\cos^{-1} [E_s / (2E_s^2 + 4Q_m \times (1 - wxc))^{1/2}]$$

$$E_{r(\text{crit})} = [E_s \cos \delta_{r(\text{crit})} + E_s^2 \cos^2 \delta_{r(\text{crit})} + 4Q_m X (1 - wxc)] / 2(1 - wxc)$$

$$P_{r(\text{crit})} = (E_s E_{r(\text{crit})} / X + \cos \delta_{r(\text{crit})} + \theta) - (E_{r(\text{crit})}^2 \cos \theta) / X$$

$s.m.^{\circ}$ = found from (B -2)

go to **Step 8**

Step 8: Compute the required angle and reactive power at receiving end :

$\delta_{r(req)}^{\circ}$ = found from (A - 1)

$Q_{r(req)}^{\circ} = P_{r(crit)} (1 - wxc - \cos \delta_{r(req)}^{\circ})$

If $Q_{r(req)}^{\circ} \leq Q_m$ go to **Step 9**

If $(Q_{r(req)}^{\circ} > Q_m)$ go to **Step 10**

Step 9: Compute, $E_r^{\circ} = E_s$

δ_r° = found from (B - 1)

(stop)

Step 10: Compute,

$$C_1 = E_s (Q_m^2 + P_r^{\circ 2})^{1/2}$$

$$C_2 = \tan^{-1} (P_r^{\circ} / Q_m)$$

$$C_3 = Q_m E_s^2 - 2X(1 - wxc)P_r^{\circ 2}$$

$$\delta_r^{\circ} = \frac{1}{2} (C_2 - \cos^{-1} (C_3/C_1))$$

$$E_r^{\circ} = XP_r^{\circ} / E_s \sin (-\delta_r^{\circ})$$

(stop)